**RESEARCH ARTICLE** 

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# Statistical approach on 3D hydromagnetic flow of water-based nanofluid between two vertical porous plates moving in opposite directions

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#### Abstract

The nanofluid flow between two plates is a common topic of research. However, studies dealing with the flow between two vertical plates moving in different directions have not been largely accounted for. The main aim of this study is to analytically and statistically investigate the MHD flow of water-based nanofluid between two vertical porous plates moving in opposite directions using perturbation technique and multiple linear regression, respectively. The consequence of various parameters on concentration, temperature, and velocity are examined via graphs using MATLAB software. It is observed that the main flow velocity profile is greater when the magnetic field is applied on the upward moving plate as compared to the main flow velocity when the magnetic field is applied on the downward-moving plate. The physical quantities are scrutinized using statistical tools like probable error and multiple linear regression and an excellent agreement is noted. It is noted that the Nusselt number is highly positively correlated with the injection parameter and highly negatively correlated with nanoparticle volume fraction. Furthermore, the simultaneous effects of parameters

on drag coefficients are studied with the aid of threedimensional surface plots.

KEYWORDS

correlation coefficient, natural convection, opposite moving plates, regression analysis, unsteady three-dimensional MHD flow, water-based nanofluid

## **1** | INTRODUCTION

Magnetohydrodynamics (MHD), the area which deals with the study of dynamics of electrically conducting fluids under the influence of magnetic field, has raised quite an interest over the years due to its versatile number of application in various fields; like in geophysics, engineering, biomedical engineering, magnetic drug targeting, and many others.

MHD is commonly paired with convective flows, which can either be natural, forced, or mixed. Natural or free convection is the type of flow where the motion is not generated by an external source. Natural convection has called in a lot of attention from the researchers with its applications ranging from engineering to nature. Sabu et al.<sup>1</sup> studied the behavior of hydromagnetic convective ferro-nanofluid flow through an inclined channel with porous medium and observed an increase in velocity with respect to Hall current. Kumar et al.<sup>2</sup> employ a numerical model to investigate the influence of thermal radiation on the nanofluid flow from an infinite vertical plate considering viscous dissipation and magnetic field. It is noted that an augmentation in radiation parameter causes an enhancement in the temperature and velocity profiles. MHD convective flow with various attributes are explained in References [3–10].

Plates containing voids (holes) are known as porous plates. The flow through porous plates has applications in chemical engineering (for filtration and clarification), agriculture (in the study of underwater resources), and petroleum industry (to study the movement of natural gas, oil, and water). Biswal et al.<sup>11</sup> elucidated the influence of transverse magnetic effect on the flow of water-based fluid with added silver and copper nanoparticles in a semiporous channel using the least square method. A great deal of studies has been carried out in problems dealing with the MHD flow in a porous channel as well as parallel plates.<sup>12–21</sup>

Nanofluids have been a hot topic for a while now. Using nanofluids instead of the normal base fluids has yielded many awarding results. It is seen that nanofluids have better convective heat transfer capabilities. Kiyani et al.<sup>22</sup> semianalytically investigated the bidirectional Williamson nanofluid flow in porous space using optimal homotopy asymptotic method (OHAM) and observed that space- and temperature-dependent heat sources have a positive effect on temperature. Kumar et al.<sup>23</sup> studied magnetite water-based nanofluid flow over a rotating disk in the presence of an external magnetic field and Arrhenius activation energy using fourth-order Noumerov's method and noted that the thermophoresis parameter has a negative impact on heat transfer rate. Hazarika et al.<sup>24</sup> used the fourth-order Runge-Kutta-shooting technique to numerically investigate the MHD flow of a chemically reacting water-based nanofluid over a permeable stretching sheet involving chemical reaction, thermophoresis, heat source, and viscous dissipation. Seth et al.<sup>25</sup> examined the unsteady hydromagnetic boundary layer flow of a thermally radiating nanofluid considering Navier's velocity slip and external magnetic field past nonlinear stretching sheet placed in a porous medium using

OHAM. Furthermore, linear and quadratic multiple linear regression analysis was exercised in scrutinizing the effect of pertinent parameters on Nusselt number and drag coefficient.

The use of statistical tools for analyzing the effects of numerous physical parameters has intrigued a lot of researchers. A countable number of works, where the ideas of correlation, slope of linear regression, probable error, and regression analysis are used to compare and analyze the outcome of various physical quantities,<sup>1,26–32</sup> have been published.

Many researchers have analyzed the hydromagnetic flow between two vertical porous plates due to free convection and varying geometrical shapes. However, only a countable number of works involving MHD-free convective flow between two vertical porous plates moving in differing direction<sup>33–36</sup> have been published. Previous studies were based on conventional (base) fluids, whereas the present study extends the problem into nanoscale. The current problem finds its application in several engineering, geophysical, and industrial fields. The problem is solved using the perturbation technique. Results are presented with the help of tables and graphs. Mass and heat transfer rates are analyzed and modeled using statistical tools like probable error and regression.

## 2 | PROBLEM STATEMENT

An unsteady hydromagnetic fluctuating flow of a water-based nanofluid between two insulated vertical porous plates is considered (Figure 1). The problem is studied under the following assumptions:

- (i) Plates are moving in opposite directions with uniform velocity.
- (ii) The upward moving plate is subjected to a transverse sinusoidal injection velocity, whereas the downward-moving plate is subjected to a constant suction velocity.
- (iii) A magnetic field of uniform strength is applied perpendicular to the plane of the plate.
- (iv) The induced magnetic field has been neglected due to the assumption of a small magnetic Reynolds number.
- (v) The nanofluid constants are taken in accordance with Table 1.
- (vi) The injection velocity distribution is of the form

Effective dynamic viscosity	$\frac{1}{A_1} = \frac{\mu_{nf}}{\mu_f} = \frac{1}{(1-\phi)^{2.5}}$
Effective density	$A_2=rac{ ho_{nf}}{ ho_f}=(1-\phi)+\phiiggl(rac{ ho_s}{ ho_f}iggr)$
Effective electrical conductivity	$A_3 = \frac{\sigma_{nf}}{\sigma_f} = 1 + \frac{3\left(\frac{\sigma_8}{\sigma_f} - 1\right)\phi}{\left(\frac{\sigma_8}{\sigma_f} + 2\right) - \left(\frac{\sigma_8}{\sigma_f} - 1\right)\phi}$
Effective coefficient of thermal expansion	$A_4=rac{eta_{nf}}{eta_f}=(1-oldsymbol{\phi})+oldsymbol{\phi}iggl(rac{eta_{ m s}}{eta_f}iggr)$
Effective specific heat	$A_5 = \frac{(\rho C_p)_{nf}}{(\rho C_p)_f} = (1 - \phi) + \phi \left( \frac{(\rho C_p)_s}{(\rho C_p)_f} \right)$
Effective thermal conductivity	$A_6 = \frac{\kappa_{nf}}{\kappa_f} = \frac{\kappa_s + 2\kappa_f - 2\phi(\kappa_f - \kappa_s)}{\kappa_s + 2\kappa_f + 2\phi(\kappa_f - \kappa_s)}$

#### TABLE 1 Nanofluid constants

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$$v^*(z^*) = V_0(1 + \varepsilon_1 \cos(\pi z^*/d)).$$

- (vii) Without loss of generality, the distance d between the plates is taken equal to the wavelength of the injection velocity.
- (viii) The temperature of the upward moving plate fluctuating with time is given as

$$T^*(t^*) = T_0 + \varepsilon_2 (T_0 - T_1) e^{i\omega^* t^*}.$$

(ix) The concentration of the upward moving plate fluctuating with time is given as

$$C^*(t^*) = \mathcal{C}_0 + \varepsilon_3(\mathcal{C}_0 - \mathcal{C}_1)e^{i\omega^*t^*}.$$

(x) The temperature and concentration of the downward-moving plate are at constant temperature  $T_1$  and constant concentration  $C_1$ , respectively.

Using the above assumptions and Boussinesq's approximation, the governing equations<sup>33</sup> takes the form:

$$\frac{\partial v^*}{\partial y^*} + \frac{\partial w^*}{\partial z^*} = 0, \tag{1}$$

$$\frac{\partial u^*}{\partial t^*} + v^* \frac{\partial u^*}{\partial y^*} + w^* \frac{\partial u^*}{\partial z^*} = -\frac{1}{\rho_{\rm nf}} \left[ \frac{\partial p^*}{\partial x^*} - \mu_{\rm nf} \left( \frac{\partial^2 u^*}{\partial y^{*2}} + \frac{\partial^2 u^*}{\partial z^{*2}} \right) + \sigma_{\rm nf} B_0^2 u^* \right] + g\beta_{\rm nf} \left( T^* - T_1 \right) \\ + g\beta_{\rm nf} \left( C^* - C_1 \right), \tag{2}$$

$$\frac{\partial v^*}{\partial t^*} + v^* \frac{\partial v^*}{\partial y^*} + w^* \frac{\partial v^*}{\partial z^*} = -\frac{1}{\rho_{\rm nf}} \left[ \frac{\partial p^*}{\partial y^*} - \mu_{\rm nf} \left( \frac{\partial^2 v^*}{\partial y^{*2}} + \frac{\partial^2 v^*}{\partial z^{*2}} \right) \right],\tag{3}$$

$$\frac{\partial w^*}{\partial t^*} + v^* \frac{\partial w^*}{\partial y^*} + w^* \frac{\partial w^*}{\partial z^*} = -\frac{1}{\rho_{\rm nf}} \left[ \frac{\partial p^*}{\partial z^*} - \mu_{\rm nf} \left( \frac{\partial^2 w^*}{\partial y^{*2}} + \frac{\partial^2 w^*}{\partial z^{*2}} \right) + \sigma_{\rm nf} B_0^2 w^* \right],\tag{4}$$

$$\frac{\partial T^*}{\partial t^*} + v^* \frac{\partial T^*}{\partial y^*} + w^* \frac{\partial T^*}{\partial z^*} = \frac{\kappa_{\rm nf}}{(\rho c_p)_{\rm nf}} \left[ \frac{\partial^2 T^*}{\partial y^{*2}} + \frac{\partial^2 T^*}{\partial z^{*2}} \right],\tag{5}$$

$$\frac{\partial C^*}{\partial t^*} + v^* \frac{\partial C^*}{\partial y^*} + w^* \frac{\partial C^*}{\partial z^*} = D_B \left( \frac{\partial^2 C^*}{\partial y^{*2}} + \frac{\partial^2 C^*}{\partial z^{*2}} \right) - K_l (C^* - C_1).$$
(6)

The boundary conditions for the problem are:

$$y^{*} = 0, u^{*} = U_{0}, v^{*}(z^{*}) = V_{0}\left(1 + \varepsilon_{1}\cos\frac{\pi z^{*}}{d}\right), w^{*} = 0,$$

$$T^{*}(t^{*}) = T_{0} + \varepsilon_{2}(T_{0} - T_{1})e^{i\omega^{*}t^{*}}, C^{*}(t^{*}) = C_{0} + \varepsilon_{3}(C_{0} - C_{1})e^{i\omega^{*}t^{*}}$$

$$y^{*} = d, u^{*} = -U_{0}, v^{*}(z^{*}) = V_{0}, w^{*} = 0, T^{*} = T_{1}, C^{*} = C_{1}$$

$$(7)$$

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Introducing the following nondimensional quantities

$$y = \frac{y^*}{d}, z = \frac{z^*}{d}, t = t^* \omega^*, u = \frac{u^*}{U_0}, v = \frac{v^*}{V_0}, w = \frac{w^*}{V_0}, \omega = \frac{\omega^* d^2}{\vartheta}, p = \frac{p^*}{\rho_{\rm nf} V_0^2}, \theta = \frac{T^* - T_1}{T_0 - T_1}, C = \frac{C^* - C_1}{C_0 - C_1}$$

into Equations (1)–(7), excluding (2) we get:

$$\frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0, \tag{8}$$

$$\frac{\omega}{Re}\frac{\partial v}{\partial t} + v\frac{\partial v}{\partial y} + w\frac{\partial v}{\partial z} = -\frac{\partial p}{\partial y} + \frac{1}{A_1 A_2 Re} \left(\frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2}\right),\tag{9}$$

$$\frac{\omega}{Re}\frac{\partial w}{\partial t} + v\frac{\partial w}{\partial y} + w\frac{\partial w}{\partial z} = -\frac{\partial p}{\partial z} + \frac{1}{A_1A_2Re}\left(\frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2}\right) - \frac{A_3}{A_2Re}H^2w,$$
(10)

$$\frac{\omega}{Re}\frac{\partial\theta}{\partial t} + v\frac{\partial\theta}{\partial y} + w\frac{\partial\theta}{\partial z} = \frac{A_6}{A_5 PrRe} \left(\frac{\partial^2\theta}{\partial y^2} + \frac{\partial^2\theta}{\partial z^2}\right),\tag{11}$$

$$\frac{\omega}{Re}\frac{\partial C}{\partial t} + v\frac{\partial C}{\partial y} + w\frac{\partial C}{\partial z} = \frac{1}{ReSc} \left(\frac{\partial^2 C}{\partial y^2} + \frac{\partial^2 C}{\partial z^2}\right) - \frac{Kr}{Re}C.$$
(12)

Equation (2) reduces to the following partial differential equations based on the two cases: *Case* 1: Magnetic field is applied on the upward moving plate (at y = 0)

$$\frac{\omega}{Re}\frac{\partial u}{\partial t} + v\frac{\partial u}{\partial y} + w\frac{\partial u}{\partial z} = \frac{1}{A_1A_2Re}\left(\frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2}\right) - \frac{A_3}{A_2Re}H^2(u-1) + A_4GrRe\theta + A_4GmReC.$$
<sup>(13)</sup>

*Case 2*: Magnetic field is applied on the downward-moving plate (at y = 1)

$$\frac{\omega}{Re}\frac{\partial u}{\partial t} + v\frac{\partial u}{\partial y} + w\frac{\partial u}{\partial z} = \frac{1}{A_1A_2Re} \left(\frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2}\right) - \frac{A_3}{A_2Re}H^2(u+1) + A_4GrRe\theta + A_4GmReC,$$
<sup>(14)</sup>

where the nondimensional parameters are explained in the nomenclature.

The boundary conditions in the nondimensional form are given by

$$y = 0, \quad u = 1, \quad v(z) = 1 + \varepsilon_1 \cos \pi z, \quad w = 0, \quad \theta = 1 + \varepsilon_2 e^{it}, \quad C = 1 + \varepsilon_3 e^{it}$$

$$y = 1, \quad u = -1, \quad v = 1, \quad w = 0, \quad \theta = 0, \quad C = 0$$

$$(15)$$

#### 3 | METHODOLOGY

Since  $\varepsilon = \min \{\varepsilon_1, \varepsilon_2, \varepsilon_3\}$  is very small, we assume that the solution of the problem is of the form

$$f(y, z, t) = f_0(y) + \varepsilon f_1(y, z, t) + O(\varepsilon^2).$$
<sup>(16)</sup>

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# 3.1 | Steady flow solution

When  $\varepsilon = 0$ , the current problem contracts to a steady two-dimensional hydromagnetic flow between two vertical porous plates moving in different directions with uniform injection/ suction, which is governed by the following equations:

*Case* 1: Magnetic field is applied on the upward moving plate (at y = 0)

$$u_0'' - A_1 A_2 Reu_0' - A_1 A_3 H^2(u_0 - 1) + A_1 A_2 A_4 Re^2 Gr \theta_0 + A_1 A_2 A_4 Re^2 Gm C_0 = 0.$$
<sup>(17)</sup>

*Case* 2: Magnetic field is applied on the downward moving plate (at y = 1)

$$u_0'' - A_1 A_2 Reu_0' - A_1 A_3 H^2(u_0 + 1) + A_1 A_2 A_4 Re^2 Gr \theta_0 + A_1 A_2 A_4 Re^2 Gm C_0 = 0,$$
<sup>(18)</sup>

with  $v_0 = 1$ ,  $w_0 = 0$ ,  $p_0 = \text{constant}$  and

$$\theta_0'' - \frac{A_5 PrRe}{A_6} \theta_0' = 0, \tag{19}$$

$$C_0'' - ScReC_0' - KrScC_0 = 0,$$
(20)

where primes denote the derivative with respect to y.

The corresponding boundary condition for the above two cases reduce to:

$$y = 0, u_0 = 1, \theta_0 = 1, C_0 = 1 y = 1, u_0 = -1, \theta_0 = 0, C_0 = 0$$
 (21)

The solutions of Equations (17)–(20) subject to (21) are:

$$\theta_0 = \frac{1}{e^a - 1} (e^a - e^{ay}), \tag{22}$$

$$C_0 = \frac{1}{(e^{m_2} - e^{m_1})} (e^{m_2} e^{m_1 y} - e^{m_1} e^{m_2 y}).$$
<sup>(23)</sup>

Case 1: Magnetic field is applied on the upward moving plate (at y = 0)

$$u_{0} = \frac{1}{(e^{m_{4}} - e^{m_{3}})} ((\alpha_{1}e^{m_{4}} - \beta_{1})e^{m_{3}y} + (\beta_{1} - \alpha_{1}e^{m_{3}})e^{m_{4}y}) + B_{1}e^{ay} + B_{2}e^{m_{1}y} + B_{3}e^{m_{2}y} + B_{4} + 1$$
(24)

*Case 2*: Magnetic field is applied on the downward moving plate (at y = 1)

$$u_{0} = \frac{1}{(e^{m_{4}} - e^{m_{3}})} (((\alpha_{1} + 2)e^{m_{4}} - (\beta_{1} + 2))e^{m_{3}y} + ((\beta_{1} + 2) - (\alpha_{1} + 2)e^{m_{3}})e^{m_{4}y}) + B_{1}e^{ay} + B_{2}e^{m_{1}y} + B_{3}e^{m_{2}y} + B_{4} - 1.$$
(25)

#### 3.2 | Cross flow solution

When  $\varepsilon \neq 0$ , substituting Equation (16) in Equations (8)–(10) and comparing the coefficients of  $\varepsilon$  and neglecting the terms with  $O(\varepsilon^2)$ , we obtain the following first-order equations:

$$\frac{\partial v_1}{\partial y} + \frac{\partial w_1}{\partial z} = 0, \tag{26}$$

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$$\frac{\omega}{Re}\frac{\partial v_1}{\partial t} + \frac{\partial v_1}{\partial y} = -\frac{\partial p_1}{\partial y} + \frac{1}{A_1 A_2 Re} \left(\frac{\partial^2 v_1}{\partial y^2} + \frac{\partial^2 v_1}{\partial z^2}\right),\tag{27}$$

$$\frac{\omega}{Re}\frac{\partial w_1}{\partial t} + \frac{\partial w_1}{\partial y} = -\frac{\partial p_1}{\partial z} + \frac{1}{A_1A_2Re}\left(\frac{\partial^2 w_1}{\partial y^2} + \frac{\partial^2 w_1}{\partial z^2}\right) - \frac{A_3}{A_2Re}H^2w_1.$$
(28)

Corresponding boundary conditions are

$$y = 0, v_1 = \cos \pi z, w_1 = 0 \\ y = 1, v_1 = 0, w_1 = 0$$
 (29)

These are the linear partial differential equations describing the three-dimensional crossflow, which is independent of the main flow component,  $u_1$ , temperature field,  $\theta_1$ , and concentration field,  $C_1$ .

Assume that the solutions for  $v_1$ ,  $w_1$ ,  $p_1$  are of the form:

$$v_1(y, z, t) = v_{11}(y)e^{it} + v_{12}(y)\cos\pi z,$$
(30)

$$w_1(y, z, t) = -\left(zv_{11}'(y)e^{it} + \frac{1}{\pi}v_{12}'(y)\sin\pi z)\right),\tag{31}$$

$$p_1(y, z, t) = p_{11}(y)e^{it} + p_{12}(y)\cos\pi z,$$
(32)

where prime denotes the derivative with respect to y. Expressions (30) and (31) are chosen in such a way that the continuity Equation (26) is precisely satisfied. Substituting these into Equations (27) and (28) and applying Equation (29), we obtain the solutions of  $v_1$ ,  $w_1$ ,  $p_1$  as:

$$\nu_1 = \frac{1}{D} \sum_{i=1}^{4} D_i e^{r_i y} \cos \pi z,$$
(33)

$$w_1 = -\frac{1}{\pi D} \sum_{i=1}^{4} r_i D_i e^{r_i y} \sin \pi z,$$
(34)

$$p_1 = \frac{1}{A_1 A_2 R e \pi^2 D} \sum_{i=1}^4 D_i (r_i^3 - A_1 A_2 R e r_i^2 - (A_1 A_3 H^2 + \pi^2) r_i) e^{r_i y} \cos \pi z.$$
(35)

# 3.3 | Temperature and concentration field

Similarly, using Equation (16) when  $\varepsilon \neq 0$ , the first-order equation for temperature and concentration fields are

$$\frac{\omega}{Re}\frac{\partial\theta_1}{\partial t} + \frac{\partial\theta_1}{\partial y} = \frac{A_6}{A_5 Pr Re} \left(\frac{\partial^2\theta_1}{\partial y^2} + \frac{\partial^2\theta_1}{\partial z^2}\right),\tag{36}$$

$$\frac{\omega}{Re}\frac{\partial C_1}{\partial t} + \frac{\partial C_1}{\partial y} = \frac{1}{ReSc} \left( \frac{\partial^2 C_1}{\partial y^2} + \frac{\partial^2 C_1}{\partial z^2} \right) - \frac{Kr}{Re} C_1, \tag{37}$$

with corresponding boundary conditions

$$y = 0, \theta_1 = e^{it}, C_1 = e^{it} \\ y = 1, \theta_1 = 0, C_1 = 0$$
(38)

Equations (36)–(38) are solved with an assumption that the solutions are of the form:

$$\theta_1(y, z, t) = \theta_{11} e^{it} + \theta_{12} \cos \pi z, \tag{39}$$

$$C_1(y, z, t) = C_{11}e^{it} + C_{12}\cos\pi z.$$
<sup>(40)</sup>

Substituting Equations (39) and (40) in (36) and (37), respectively we get

$$\theta_{11}'' - \frac{A_5 Pr Re}{A_6} \theta_{11}' - \frac{A_5 Pr \omega i}{A_6} \theta_{11} = 0, \tag{41}$$

$$\theta_{12}'' - \frac{A_5 Pr Re}{A_6} \theta_{12}' - \pi^2 \theta_{12} = 0, \qquad (42)$$

$$C_{11}'' - ScReC_{11}' - (Sc\omega i + KrSc)C_{11} = 0,$$
(43)

$$C_{12}'' - ScReC_{12}' - (ScKr + \pi^2)C_{12} = 0,$$
<sup>(44)</sup>

with the corresponding transformed boundary conditions

$$y = 0, \theta_{11} = 1, \theta_{12} = 0, C_{11} = 1, C_{12} = 0$$
  

$$y = 1, \theta_{11} = 0, \theta_{12} = 0, C_{11} = 0, C_{12} = 0$$
(45)

Solving Equations (41)-(44) under the boundary condition (45), the solutions are obtained as

$$\theta_1(y, z, t) = \frac{1}{e^{n_2} - e^{n_1}} (e^{n_2} e^{n_1 y} - e^{n_1} e^{n_2 y}) e^{it}, \tag{46}$$

$$C_1(y, z, t) = \frac{1}{e^{m_6} - e^{m_5}} (e^{m_6} e^{m_5 y} - e^{m_5} e^{m_6 y}) e^{it}.$$
 (47)

# 3.4 | Main flow solution

When  $\varepsilon \neq 0$ , with the aid of Equation (16) and comparing coefficients of  $\varepsilon$ , we deduce the firstorder equation for the main flow component,  $u_1$  as:

$$\frac{\omega}{Re}\frac{\partial u_1}{\partial t} + \frac{\partial u_1}{\partial y} + v_1 u_0' = \frac{1}{A_1 A_2 Re} \left( \frac{\partial^2 u_1}{\partial y^2} + \frac{\partial^2 u_1}{\partial z^2} \right) - \frac{A_3}{A_2 Re} H^2 u_1 + A_4 Gr Re\theta_1 +$$

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( = 1 )

The corresponding boundary conditions are:

$$y = 0, u_1 = 0 y = 1, u_1 = 0$$
 (49)

To solve the above differential equation for the main flow velocity component,  $u_1(y, z, t)$ , we assume that the solution is of the form:

$$u_1(y, z, t) = u_{11}e^{it} + u_{12}\cos\pi z.$$
<sup>(50)</sup>

Substituting Equation (50) in (48) and neglecting terms of  $O(\varepsilon^2)$  we obtain:

$$u_{11}'' - A_1 A_2 Reu_{11}' - (A_1 A_2 \omega i + A_1 A_3 H^2) u_{11} = -A_1 A_2 A_4 Re^2 Gr \theta_{11} - A_1 A_2 A_4 Re^2 Gm C_{11},$$
<sup>(51)</sup>  
$$u_{12}'' - A_1 A_2 Reu_{12}' - (\pi^2 + A_1 A_3 H^2) u_{12} = A_1 A_2 Rev_{12} u_0',$$
<sup>(52)</sup>

with

$$y = 0, u_{11} = 0, u_{12} = 0 y = 1, u_{11} = 0, u_{12} = 0$$
(53)

Solving Equations (51) and (52) considering (53) and using (50), we derive the solutions as: *Case* 1: Magnetic Field is applied on the upward moving plate (at y = 0)

$$u_{1}(y, z, t) = \begin{cases} \frac{1}{e^{r_{6}} - e^{r_{5}}} [(\alpha_{2}e^{r_{6}} - \beta_{2})e^{r_{5}y} + (\beta_{2} - \alpha_{2}e^{r_{5}})e^{r_{6}y}] + K_{1}e^{n_{1}y} \\ + K_{2} e^{n_{2}y} + K_{3}e^{m_{5}y} + K_{4}e^{m_{6}y} \end{cases} e^{it} \\ + \begin{cases} \frac{1}{e^{n_{4}} - e^{n_{3}}} [(\alpha_{3}e^{n_{4}} - \beta_{3})e^{n_{3}y} + (\beta_{3} - \alpha_{3}e^{n_{3}})e^{n_{4}y}] \\ + \sum_{i=1}^{4} (K_{i1}e^{(r_{i} + m_{3})y} + K_{i2}e^{(r_{i} + m_{4})y} + K_{i3}e^{(r_{i} + a)y} + K_{i4}e^{(r_{i} + m_{1})y} + K_{i5}e^{(r_{i} + m_{2})y}) \end{cases} cos\pi z$$

$$(54)$$

*Case* 2: Magnetic Field is applied on the downward moving plate (at y = 1)

$$u_{1}(y, z, t) = \begin{cases} \frac{1}{e^{r_{6}} - e^{r_{5}}} [(\alpha_{2}e^{r_{6}} - \beta_{2})e^{r_{5}y} + (\beta_{2} - \alpha_{2}e^{r_{5}})e^{r_{6}y}] + K_{1}e^{n_{1}y} \\ + K_{2} e^{n_{2}y} + K_{3}e^{m_{5}y} + K_{4}e^{m_{6}y} \end{cases} e^{it} \\ + \begin{cases} \frac{1}{e^{n_{4}} - e^{n_{3}}} [(\alpha_{4}e^{n_{4}} - \beta_{4})e^{n_{3}y} + (\beta_{4} - \alpha_{4}e^{n_{3}})e^{n_{4}y}] \\ + \sum_{i=1}^{4} (M_{i1}e^{(r_{i}+m_{3})y} + M_{i2}e^{(r_{i}+m_{4})y} + M_{i3}e^{(r_{i}+a)y} + M_{i4}e^{(r_{i}+m_{1})y} + M_{i5}e^{(r_{i}+m_{2})y}) \end{cases} cos\pi z \end{cases}$$
(55)

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# **4** | DRAG COEFFICIENT AND TRANSFER RATES

For practical analysis of the problem, scientists, and engineers are always interested in understanding the physical quantities like Sherwood number, Nusselt number, and skin-friction coefficients as they measure the rate of mass and heat transfer and surface drag, respectively. Their modified form<sup>33</sup> are given by:

$$Sh = \frac{d}{D_B \left( \mathcal{C}_0 - \mathcal{C}_1 \right)} \left| D_B \left( \frac{dC^*}{dy^*} \right)_{y^* = d} \right| = \left| \left( \frac{dC_0}{dy} \right)_{y=1} + \varepsilon \left( \frac{dC_1}{dy} \right)_{y=1} \right|, \tag{56}$$

$$Nu = \frac{d}{\kappa_f (T_0 - T_1)} \left| \kappa_{nf} \left( \frac{dT^*}{dy^*} \right)_{y^* = d} \right| = A_6 \left| \left( \frac{d\theta_0}{dy} \right)_{y=1} + \varepsilon \left( \frac{d\theta_1}{dy} \right)_{y=1} \right|.$$
(57)

*Case* 1: Magnetic field is applied on the upward moving plate (at y = 0)

$$Cf = \frac{d}{\mu_f U_0} \left| \mu_{\rm nf} \left( \frac{du^*}{dy^*} \right)_{y^* = d} \right| = \frac{1}{A_1} \left| \left( \frac{du_0}{dy} \right)_{y=1} + \varepsilon \left( \frac{du_1}{dy} \right)_{y=1} \right|.$$
(58)

*Case* 2: Magnetic field is applied on the downward moving plate (at y = 1)

$$Cf = \frac{d}{\mu_{\rm f} U_0} \left| \mu_{\rm nf} \left( \frac{du^*}{dy^*} \right)_{y^* = d} \right| = \frac{1}{A_1} \left| \left( \frac{du_0}{dy} \right)_{y=1} + \varepsilon \left( \frac{du_1}{dy} \right)_{y=1} \right|.$$
(59)

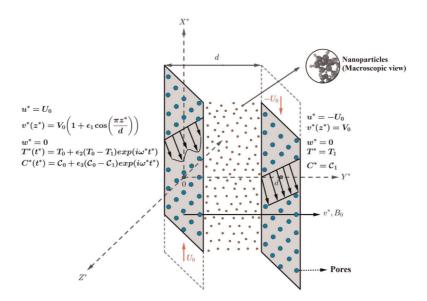


FIGURE 1 Figurative representation [Color figure can be viewed at wileyonlinelibrary.com]

HEAT TRANSFER -WILE

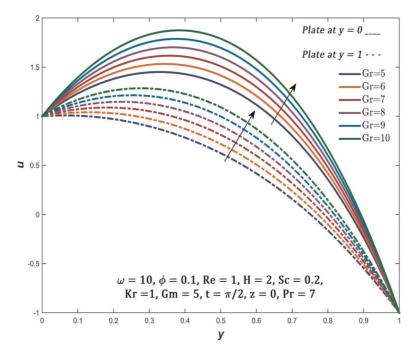


FIGURE 2 Change in *u* with *Gr* [Color figure can be viewed at wileyonlinelibrary.com]

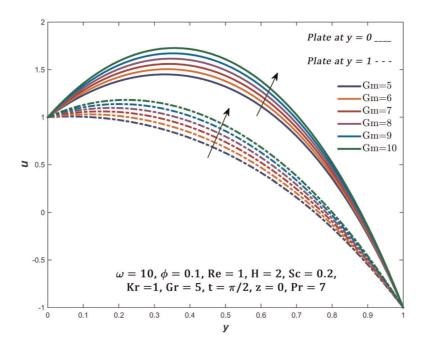
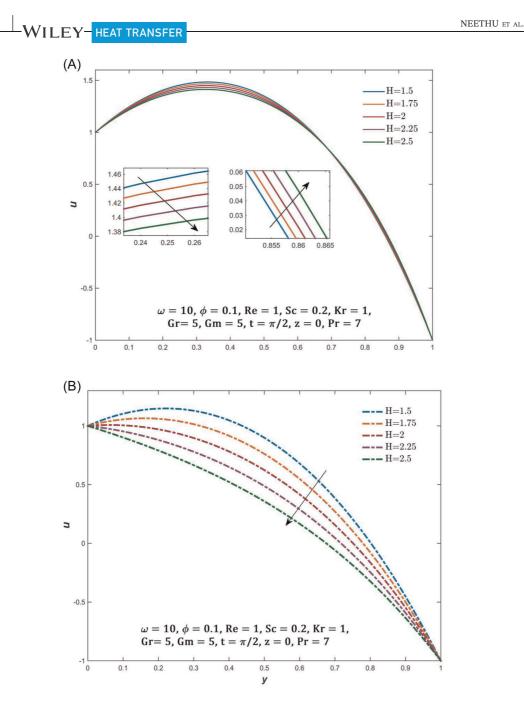


FIGURE 3 Change in *u* with *Gm* [Color figure can be viewed at wileyonlinelibrary.com]

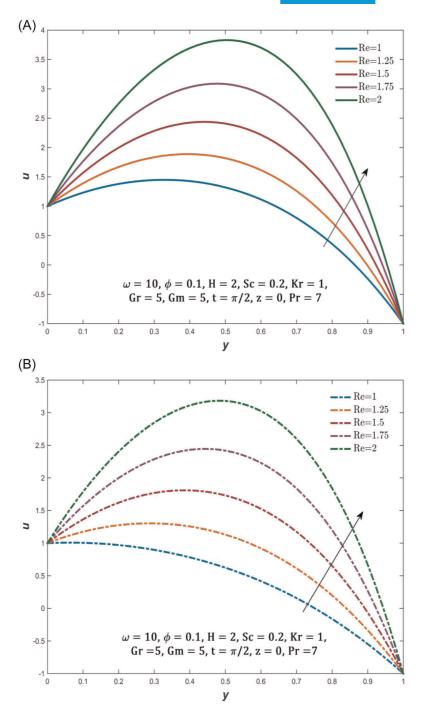


**FIGURE 4** (A) Change in *u* with *H* for plate at y = 0. (B) Change in *u* with *H* for plate at y = 1 [Color figure can be viewed at wileyonlinelibrary.com]

# **5** | **RESULTS AND DISCUSSIONS**

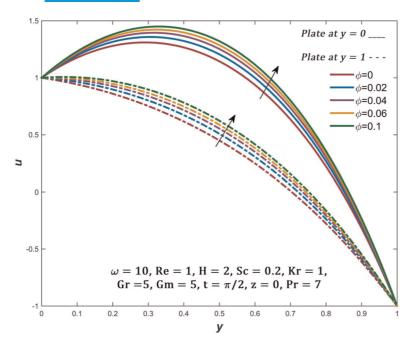
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The impact of various nanofluids, the volume fraction of nanoparticle ( $\phi$ ), Grashof number (*Gr*), chemical reaction parameter (*Kr*), injection/suction parameter (*Re*), Schmidt number (*Sc*), Hartmann number (*H*), and modified Grashof number (*Gm*) on concentration (*C*), temperature

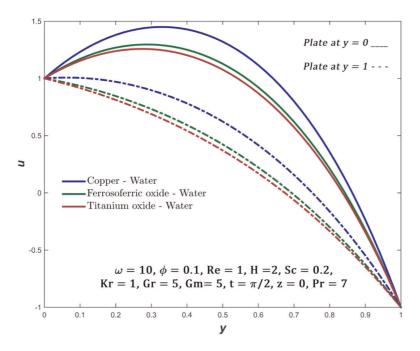


**FIGURE 5** (A) Change in *u* with *Re* for plate at y = 0. (B) Change in *u* with *Re* for plate at y = 1 [Color figure can be viewed at wileyonlinelibrary.com]

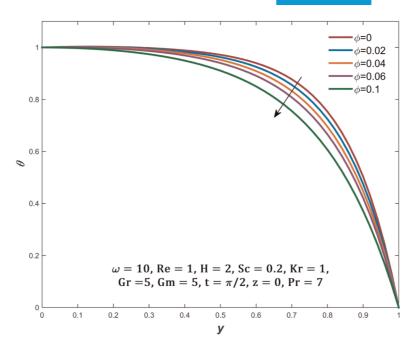




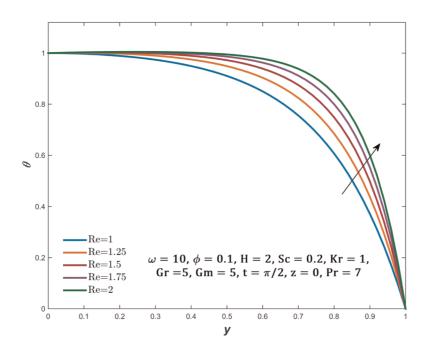
**FIGURE 6** Change in *u* with  $\phi$  [Color figure can be viewed at wileyonlinelibrary.com]



**FIGURE 7** Change in *u* with different nanofluids [Color figure can be viewed at wileyonlinelibrary.com]



**FIGURE 8** Change in  $\theta$  with  $\phi$  [Color figure can be viewed at wileyonlinelibrary.com]

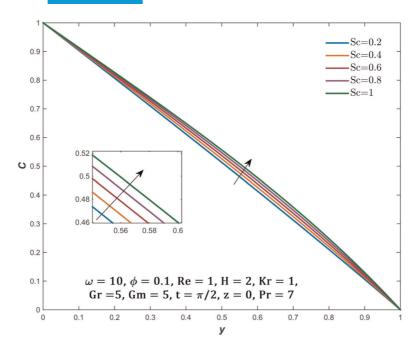


**FIGURE 9** Change in  $\theta$  with *Re* [Color figure can be viewed at wileyonlinelibrary.com]

( $\theta$ ), and velocity (u) profiles are analyzed in Figures 2–10. The analysis has been carried out for Cu–H<sub>2</sub>O nanofluid at z = 0,  $t = \pi/2$  and Pr = 7. The thermophysical properties of the base fluid and nanoparticles are given in Table 2.

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**FIGURE 10** Change in C with Sc [Color figure can be viewed at wileyonlinelibrary.com]

Physical properties	$H_2O^1$	Cu <sup>30</sup>	TiO <sub>2</sub> <sup>30</sup>	$\operatorname{Fe_3O_4}^1$
ρ	997.1	8933	4250	5180
$C_p$	4179	385	686.2	670
β	$21 \times 10^5$	$1.67 \times 10^{5}$	$0.9 \times 10^5$	$1.3 \times 10^{5}$
σ	$5 \times 10^{-2}$	$5.96 \times 10^{7}$	$2.38 \times 10^{6}$	25000
κ	0.613	400	8.9538	9.7

TABLE 2 Thermophysical properties of base fluid and nanoparticles

The consequence of Gr, the ratio of buoyancy force to viscous force, on u is presented in Figure 2. An increase in Gr causes augmentation in u for both cases (magnetic field fixed with the upward and downward moving plate). Physically, an increase in Gr paves to the increase in buoyancy force, which, in turn, increases the velocity. Figure 3 confirms that u increases in both cases when Gm is increased, the physical reason being the increase in buoyancy force due to a concentration difference. The influence of H, ratio of electromagnetic force to the viscous force, on u is graphed in Figure 4A,B. It is evident that a rise in H drastically reduces the velocity in the case of a downward moving plate. Physically, this is due to the fact that the presence of a magnetic field induces a Lorentz force against the fluid flow, which retards the velocity profile. However, in the case of an upward-moving plate, H expresses a mixed behavior on u. In the beginning, an increase in H reduces the velocity, but after a certain distance, the behavior is reversed. Figure 5A,B illustrates the exponential increase in u{both cases} corresponding to the augmentation in Re. Figure 6 depicts the positive impact of  $\phi$  on u. The impact of various nanofluids (water-based Cu/Fe<sub>3</sub>O<sub>4</sub>/TiO<sub>2</sub> nanofluid) on u is depicted in Figure 7.

t	φ	ω	Re	Nu	Enhancement/ decrement rate (%)
0.5				6.967725	
1				6.980359	0.18
1.5				6.994532	0.20
Slope				0.026808	
	0.01			7.004436	
	0.02			6.996461	-0.11
	0.03			6.989177	-0.10
Slope				-0.762966	
		5		6.996461	
		6		6.985502	-0.16
		7		6.979319	-0.09
Slope				-0.008571	
			1	6.996461	
			1.1	7.693704	9.97
			1.2	8.393986	9.10
Slope				6.987624	

**TABLE 3** Variation in *Nu* for differing parameter values at y = 1 when  $\phi = 0.02$ ,  $\omega = 5$ , Re = 1,  $t = \pi/2$ , z = 0 and Pr = 7

The effect of  $\phi$  on  $\theta$  is elucidated in Figure 8.  $\phi$  has a negative impact on the temperature profile, meaning an increase in  $\phi$  fuels a decrease in  $\theta$ . Figure 9 depicts the consequence of *Re* on temperature. It is observed that *Re* induces an increase in  $\theta$ . The influence of *Sc* on *C* is illustrated in Figure 10. Concentration profile (*C*) experiences a slight increase when *Sc* values are improved.

The consequence of heat and mass transfer rate on fluctuating parameters along with the slope of linear regression via data points and the enhancement/decrement rate is assessed in Tables 3 and 4, respectively. A negative sign in slope and enhancement/decrement rate symbolizes that the corresponding parameter has a negative impact on heat and mass transfer, meaning augmentation in parameter reduces the heat and mass transfer rate, while the magnitude of slope represents the quantity of change.

It is observed that *t* and *Re* have a positive impact on *Nu* and  $\phi$ , and  $\omega$  have a negative impact on *Nu*. The respective rates (slope) are shown in Table 3. For *Sh*, when all other parameters are kept constant, *Sh* increases with an increase in  $\omega$  at the rate of 0.000322, *Re* at 0.104051, and *Sc* at 0.355898. Also, when *Kr* and *t* increases *Sh* decreases at the rate of 0.03518 and 0.00751, respectively. Figures 11 and 12 describe the parallel effect of  $\phi$  – *Re* and *H* – *Gr* on *Cf*. From 11a and 12a, it can be deduced that  $\phi$ , *Re*, *H*, and *Gr* promotes *Cf* on the upward moving plate. From 11b and 12b, it can be summarized that  $\phi$ , *Re*, and *Gr* promotes *Cf*, while *H* demotes *Cf* on the downward-moving plate.

t	ω	Re	Sc	Kr	Sh	Enhancement/ decrement rate
0.5					1.077447	
1					1.074565	-0.27
1.5					1.069938	-0.43
Slope					-0.00751	
	5				1.069202	
	6				1.069538	0.03
	7				1.069867	0.03
Slope					0.000332	
		1			1.069202	
		1.1			1.079575	0.97
		1.2			1.090013	0.97
Slope					0.104051	
			0.2		1.069202	
			0.4		1.139795	6.60
			0.6		1.211562	6.30
Slope					0.355898	
				0.5	1.086993	
				1	1.069202	-1.64
				1.5	1.051816	-1.63
Slope					-0.03518	

**TABLE 4** Variation in *Sh* for differing parameter values at y = 1 when  $\omega = 5$ , Re = 1, Sc = 0.2, Kr = 1,  $t = \pi/2$ , z = 0 and Pr = 7

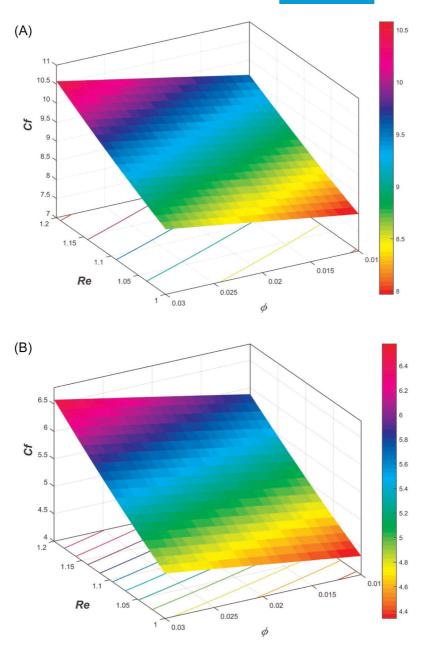
#### 6 | STATISTICAL ANALYSIS

## 6.1 | Correlation and probable error

Correlation, a statistical technique, which enables the user to find the degree of relationship between two or more variables, has gained a lot of interest in recent times. The effects of different parameters on *Nu* and *Sh* are comprehensively carried out and established using tables. A more detailed study is carried out with the help of correlation coefficient (*r*) and probable error (*PE*). The nature and the intensity of the relationship are communicated through the sign and magnitude of *r*, respectively. *PE* of *r* helps in determining the accuracy and reliability of the calculated correlation coefficient. According to Fisher,<sup>37</sup> correlation is said to be significant if  $|\frac{r}{PE}| > 6$ , where probable error,  $PE = (\frac{1-r^2}{\sqrt{n}})0.6745$  and *n* is the number of observations.

From Table 5, we can infer that Nu is highly negatively correlated with  $\phi$  and  $\omega$  and highly positively correlated with Re and t. From  $|\frac{r}{PE}|$  values, we can conclude that all parameters are significant. Table 6 proposes that Sh is highly positively correlated with  $\omega$ , Re, and Sc and highly negatively correlated with Kr and t. As earlier, we can observe that all parameters are significant.

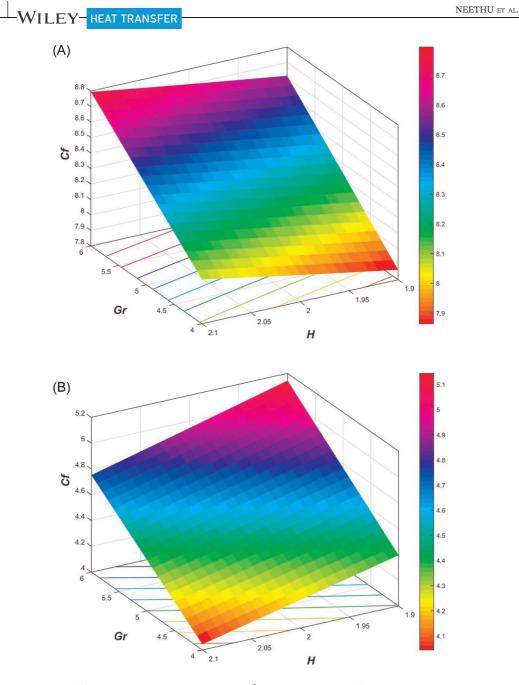
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**FIGURE 11** (A) Parallel effect of  $\phi$  and *Re* on *Cf* for plate at y = 0. (B) Parallel effect of  $\phi$  and *Re* on *Cf* for plate at y = 1 [Color figure can be viewed at wileyonlinelibrary.com]

# 6.2 | Regression analysis

All correlations are perceived to be significant and hence further analysis can be carried out using regression. Nu and Sh are estimated using multiple linear regression models. The estimated models are of the form:



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**FIGURE 12** (A) Parallel effect of *H* and *Gr* on *Cf* for plate at y = 0. (B) Parallel effect of *H* and *Gr* on *Cf* for plate at y = 1 [Color figure can be viewed at wileyonlinelibrary.com]

$$Nu_{est} = b_t t + b_{\phi} \phi + b_{\omega} \omega + b_{Re} Re + c$$
  
$$Sh_{est} = b_t t + b_{\omega} \omega + b_{Re} Re + b_{Sc} Sc + b_{Kr} Kr + c$$

where  $c, b_t, b_{\phi}, b_{\omega}, b_{Re}, b_{Sc}$  and  $b_{Kr}$  are the estimated regression coefficients.

*Nu* and *Sh* is estimated from 30 sets of values chosen in the range [0,0.04] for  $\phi$ , [5,15] for  $\omega$ , [1,1.2] for *Re*, [0.2,1] for *Sc*, [0.5,2] for *Kr*, and [0.5,  $\frac{\pi}{2}$ ] for *t* and the regression coefficients are

**TABLE 5** Correlation coefficient (*r*), probable error (*PE*) and |r/PE| values of *Nu* at y = 1 with respect to the parameters  $\phi$ ,  $\omega$ , *Re*, and *t* 

Parameter	r	PE	$\left  \frac{r}{PE} \right $
$\phi$	-0.998525054	0.000889166	1122.990857
ω	-0.96135646	0.025561445	37.60962927
Re	0.999999168	5.02117E-07	1991567.608
t	0.999450864	0.000427575	2337.487341

**TABLE 6** Correlation coefficient (*r*), probable error (*PE*) and |r/PE| values of *Sh* at y = 1 with respect to the parameters  $\omega$ , *Re*, *Sc*, *Kr*, and *t* 

Parameter	r	PE	$\left \frac{r}{PE}\right $
ω	0.999963802	2.44153E-05	40,956.47543
Re	0.999998301	1.02471E-06	975,880.9088
Sc	0.999968876	1.87766E-05	53,256.12316
Kr	-0.999947742	3.52471E-05	28,369.64913
t	-0.991117969	0.006887008	143.9112518

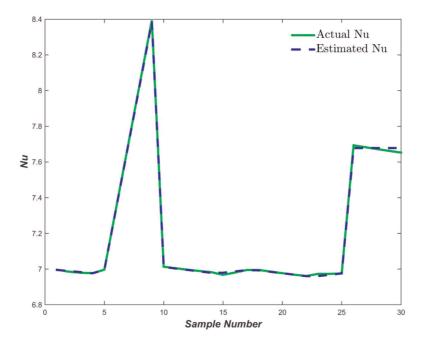


FIGURE 13 Actual Nu versus estimated Nu [Color figure can be viewed at wileyonlinelibrary.com]

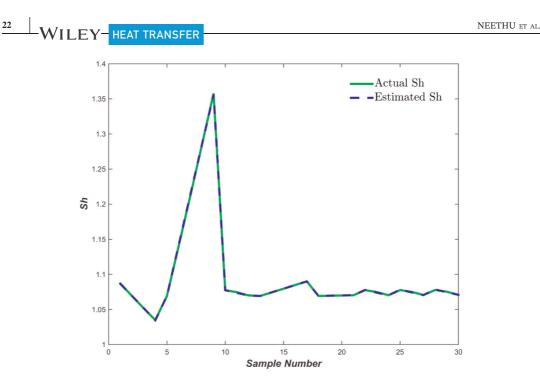


FIGURE 14 Actual Sh versus estimated Sh [Color figure can be viewed at wileyonlinelibrary.com]

found using Microsoft Excel. As the *p*-values for all the physical parameters are less than 0.05, the regression coefficients are significant. The estimated regression models are given by:

$$Nu_1^{est} = 0.014996t - 0.807981\phi - 0.006215\omega + 6.953733Re + 0.065176$$
  
$$Sh_1^{est} = -0.007645t + 0.000344\omega + 0.103518Re + 0.359017Sc - 0.034689Kr + 0.938922$$

A negative sign of the estimated regression coefficient implies that the corresponding parameter reduces the corresponding physical quantity. The estimated regression equation corresponds to the results achieved in Tables 3 and 4. Figures 13 and 14 illustrate the accuracy of the regression model for the chosen sample.

# 7 | CONCLUSION

The main conclusions drawn from the current study are listed below:

- The main flow velocity profile is directly proportional to Grashof number (*Gr*), the volume fraction of nanoparticle ( $\phi$ ), and modified Grashof number (*Gm*).
- The main flow velocity profile is greater when the magnetic field is applied on the upward moving plate as compared to the main flow velocity when the magnetic field is applied on the downward-moving plate.
- The injection parameter (Re) has a constructive effect on the main flow velocity.
- The injection parameter enhances the temperature profile, whereas the nanoparticle volume fraction diminishes the temperature profile.

- On the upward moving plate, the main flow velocity profile exhibits a mixed behavior when Hartmann number (H) is increased. Initially, the velocity reduces and after traveling a certain length the velocity increases.
- On the downward-moving plate, the velocity profile is inversely proportional to the Hartmann number-
- Schmidt number has a constructive effect on the concentration profile.
- Nusselt number is highly positively correlated with the injection parameter and highly negatively correlated with nanoparticle volume fraction.
- The regression models are found to be faultless for the chosen range of values of the parameters.

#### NOMENCLATURE

- $B_0$  strength of the magnetic field
- *C*<sup>\*</sup> fluid concentration (Moles/kg)
- $C_0$  nanoparticle concentration near the plate at origin (Moles/kg)
- $C_1$  nanoparticle concentration near the plate at *d* (Moles/kg)
- $C_p$  specific heat at constant pressure
- *d* distance between the plates
- $D_B$  chemical molecular diffusivity (m<sup>2</sup>/s)
- g acceleration due to gravity  $(m/s^2)$
- $K_l$  chemical reaction parameter
- *p*\* pressure
- $t^*$  time (s)
- *T*\* fluid temperature (K)
- $T_0$  temperature of the fluid near the plate at origin (K)
- $T_1$  temperature of the fluid near the plate at d (K)
- $u^*, v^*, w^*$  velocity components (m/s)
- $U_0$  velocity of the moving plates
- V<sub>0</sub> injection velocity

#### **GREEK SYMBOLS**

- $\sigma$  electrical conductivity
- $\phi$  volume fraction of nanoparticles
- $\mu$  dynamic viscosity (kg/m s)
- $\rho$  density (kg/m<sup>3</sup>)
- $\vartheta$  kinematic viscosity (m<sup>2</sup>/s)
- $\omega^*$  angular velocity
- $\kappa$  thermal conductivity (W/m K)
- $\varepsilon_0, \varepsilon_1, \varepsilon_2$  very small reference constants

## NONDIMENSIONAL QUANTITIES

- $Gm \;\; rac{g eta_f \vartheta_f (\mathcal{C}_0 \mathcal{C}_1)}{U_0 V_0^2};$  Modified Grashof number
- $Gr = rac{g eta_f \vartheta_f (T_0 T_1)}{U_0 V_0^2}$ ; Grashof number

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	$B_0 d \sqrt{\frac{\sigma_f}{ ho_f \vartheta_f}}$ ; Hartmann number
Kr	$\frac{K_l d^2}{\vartheta_f}$ ; chemical reaction parameter
Pr	$\frac{(\mu c_p)_f}{\kappa_f}$ ; Prandtl number
Re	$\frac{V_0 d}{\vartheta_t}$ ; injection/suction parameter

Sc  $\frac{\vartheta_f}{D}$ ; Schmidt number

#### SUBSCRIPTS

- f base fluid
- nf nanofluid
- s nanoparticle

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## APPENDIX

$$\begin{split} a &= \frac{A_{1}A_{2}}{A_{2}} & B_{1} &= \frac{A_{1}A_{2}A_{2}A_{2}B^{2}}{(e^{n}-1)(e^{2}-A_{1}A_{2}B(m)-A_{1}A_{2}B^{2})} \\ & m_{1} &= \frac{Sele - \sqrt{k^{2}Be^{2}} + 4SBK}{2} & B_{2} &= \frac{A_{1}A_{2}A_{2}B^{2}B^{2} - 4SB(m)-A_{1}A_{2}B^{2})}{(e^{m}-e^{m})\left(m^{2}-A_{1}A_{2}B(m)-A_{1}A_{2}B^{2}\right)} \\ & m_{2} &= \frac{Sele - \sqrt{k^{2}Be^{2}} + 4SB(m)}{2} & B_{3} &= \frac{A_{1}A_{2}A_{2}B^{2}B^{2} - A_{1}A_{2}B^{2}}{(e^{m}-e^{m})\left(m^{2}-A_{1}A_{2}B(m)-A_{1}A_{2}B^{2}\right)} \\ & m_{3} &= \frac{A_{1}A_{2}Be - \sqrt{A^{2}A^{2}Be^{2}} + 4SB(m)}{2} & B_{3} &= \frac{A_{1}A_{2}A_{2}B^{2}B^{2} - A_{1}A_{2}B^{2}B^{2}}{(e^{m}-e^{m})\left(m^{2}-A_{1}A_{2}B(m)-A_{1}A_{2}B^{2}\right)} \\ & m_{4} &= \frac{A_{1}A_{2}Be - \sqrt{A^{2}A^{2}Be^{2}} + 4SB(m)}{2} & B_{4} &= \frac{A_{1}A_{2}Be^{m} - A_{2}B_{1}B^{2}}{2} \\ & m_{4} &= \frac{A_{1}A_{2}Be - \sqrt{A^{2}A^{2}Be^{2}} + 4SB(m)}{2} \\ & m_{4} &= \frac{A_{1}A_{2}Be - \sqrt{A^{2}A^{2}Be^{2}} + 4SB(m)}{2} \\ & m_{4} &= \frac{A_{1}A_{2}Be - \sqrt{A^{2}A^{2}Be^{2}} + 4SB(m)}{2} \\ & m_{4} &= \frac{m_{4}-\sqrt{m^{2}+4\pi^{2}}}{2} \\ & m_{5} &= \frac{A_{1}A_{2}Be - \sqrt{A^{2}A^{2}Be^{2}} + 4SB(m)A_{2}A_{1}A_{2}B^{2}B^{2}}{2} \\ & m_{5} &= \frac{A_{1}A_{2}Be - \sqrt{A^{2}A^{2}Be^{2}} + 4SB(m)A_{2}A_{1}A_{2}B^{2}B^{2}}{2} \\ & m_{5} &= \frac{A_{1}A_{2}Be - \sqrt{A^{2}A^{2}Be^{2}} + 4SB(m)A_{2}A_{1}A_{2}B^{2}B^{2}}{2} \\ & m_{5} &= \frac{A_{1}A_{2}Be - \sqrt{A^{2}A^{2}Be^{2}} + 4SB(m)A_{2}A_{1}A_{2}B^{2}B^{2}}{2} \\ & m_{5} &= \frac{A_{1}A_{2}Be - \sqrt{A^{2}A^{2}Be^{2}} + 4SB(m)A_{2}A_{1}A_{2}B^{2}B^{2}}{2} \\ & m_{5} &= \frac{A_{1}A_{2}Be - \sqrt{A^{2}A^{2}Be^{2}} + 4SB(m)A_{2}A_{1}A_{2}B^{2}B^{2}}{2} \\ & m_{5} &= \frac{A_{1}A_{2}AE^{2}E^{-A}B^{2}}{2} \\ & m_{5} &= \frac{A_{1}A_{2}Be^{2} - (e^{1}+e^{1}) + r_{1}r_{1}(e^{1}+e^{1}-e^{1}+e^{1}) + r_{1}r_{1}(e^{1}+e^{1}-e^{1}+e^{1}) + r_{1}r_{1}(e^{1}+e^{1}-e^{1}+e^{1}) \\ & m_{5} &= \frac{A_{1}A_{2}AE^{2}E^{-A}A_{2}Be^{2}}{2} \\ & m_{5} &= \frac{SBB - \sqrt{S^{2}Be^{2} + 4SB(BB + A_{2}B^{2}B^{2}}}{2} \\ & m_{6} &= \frac{SBB - \sqrt{S^{2}Be^{2} + 4SB(BB + A_{2}B^{2}B^{2}}}{2} \\ & m_{6} &= \frac{SBB - \sqrt{S^{2}Be^{2} + 4SB(BB + A_{2}B^{2}B^{2}}}{2} \\ & m_{6} &= \frac{SBB - \sqrt{S^{2}BB^{2} + AA_{2}BB^{2}}}{2} \\ & m_{6} &= \frac{A_{1}A_{$$

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$$\begin{split} M_{i4} &= K_{i4} = \frac{m_1 B_2 A_1 A_2 Re D_i}{D \Big[ (r_i + m_1)^2 - A_1 A_2 Re (r_i + m_1) - (A_1 A_3 H^2 + \pi^2) \Big]}, i = 1,2,3,4 \\ M_{i5} &= K_{i5} = \frac{m_2 B_3 A_1 A_2 Re D_i}{D \Big[ (r_i + m_2)^2 - A_1 A_2 Re (r_i + m_2) - (A_1 A_3 H^2 + \pi^2) \Big]}, i = 1,2,3,4 \\ \alpha_3 &= -\sum_{i=1}^{4} (K_{i1} + K_{i2} + K_{i3} + K_{i4} + K_{i5}) \\ \beta_3 &= -\sum_{i=1}^{4} (K_{i1} e^{r_i + m_3} + K_{i2} e^{r_i + m_4} + K_{i3} e^{r_i + a} + K_{i4} e^{r_i + m_1} + K_{i5} e^{r_i + m_2}) \\ \alpha_4 &= -\sum_{i=1}^{4} (M_{i1} + M_{i2} + M_{i3} + M_{i4} + M_{i5}) \\ \beta_4 &= -\sum_{i=1}^{4} (M_{i1} e^{r_i + m_3} + M_{i2} e^{r_i + m_4} + M_{i3} e^{r_i + a} + M_{i4} e^{r_i + m_1} + M_{i5} e^{r_i + m_2}) \end{split}$$